

Purely Automated Attacks on PassPoints-Style Graphical Passwords

P.C. van Oorschot, Amirali Salehi-Abari, Julie Thorpe

Abstract—We introduce and evaluate various methods for purely automated attacks against PassPoints-style graphical passwords. For generating these attacks, we introduce a graph-based algorithm to efficiently create dictionaries based on heuristics such as click-order patterns (e.g., 5 points all along a line). Some of our methods combine click-order heuristics with focus-of-attention scan-paths generated from a computational model of visual attention, yielding significantly better automated attacks than previous work. One resulting automated attack finds 7-16% of passwords for two representative images using dictionaries of approximately 2^{26} entries (where the full password space is 2^{43}). Relaxing click-order patterns substantially increased the attack efficacy albeit with larger dictionaries of approximately 2^{35} entries, allowing attacks that guessed 48-54% of passwords (compared to previous results of 1% and 9% on the same dataset for two images with 2^{35} guesses). These latter attacks are independent of focus-of-attention models, and are based on image-independent guessing patterns. Our results show that automated attacks, which are easier to arrange than human-seeded attacks and are more scalable to systems that use multiple images, pose a significant threat to basic PassPoints-style graphical passwords.

Index Terms—Computer security, graphical user interfaces, machine vision, image processing, human factors, algorithms.

I. INTRODUCTION

GRAPHICAL passwords are an alternative to text passwords, whereby a user is asked to remember an image (or parts of an image) instead of a word. They are motivated in part by the well-known fact that people have superior memorability for images [19], and the promise of their suitability for small devices such as smart phones. Graphical passwords have become an active topic of research with many new proposals (see surveys [21], [29], [26]). One proposal of interest, *PassPoints* [37], [35], involves a user creating a 5-point click sequence on a background image. Usability studies have indicated that these graphical passwords have reasonable login and creation times, acceptable error rates, decent general perception [36], [37], [5], and less interference between multiple passwords [20], [11], [4] when compared to text passwords.

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Our research improves our understanding of the security of *PassPoints-style graphical passwords*, i.e., schemes closely resembling PassPoints, wherein a user creates a click sequence of r points (e.g., $r = 5$) on a single background image. PassPoints-style graphical passwords have been shown to be susceptible to hot-spots, which can be exploited in *human-seeded attacks* [31], [32], whereby human-computed data (harvesting click-points from a small set of users) is used to facilitate efficient attacks. These attacks require that the attacker collect sufficient “human-computed” data for the target image, which is more costly for systems with multiple images. This leads us to ask whether more scalable attacks exist, and in particular, effective fully-automated attacks.

To address this question, in the present work we introduce and evaluate a set of purely automated attacks against PassPoints-style graphical passwords. Our attack method is based on the hypothesis that users are more likely to choose click-points relating to predictable preferences, e.g., logically grouping the click-points through a click-order pattern (such as five points in a straight line), and/or choosing click-points in the areas of the image that their attention is naturally drawn towards. To find parts of the image that users are more likely to attend to (salient parts of the image), we use Itti et al.’s [16] model of visual attention. We also examine click-order patterns both alone and in combination with these more salient parts of the image.

Our attacks employ sets of graphical passwords that we hypothesize are “more likely” to be chosen than others; these sets naturally define dictionaries for use in a dictionary attack. A successful such attack must be able to *efficiently* generate a dictionary containing highly probable passwords. In existing literature, the *size* of a dictionary is normally considered the most important cost for a dictionary attack, whereas the cost of dictionary generation is often neglected; the latter is reasonable if a one-time precomputation can be reused. Alternately, if the dictionary must be generated on-the-fly, or recomputed each time (e.g., for a different background image), then the cost of dictionary generation may become as or more important than the size of the dictionary itself.

We present a graph-based algorithm for attack dictionary generation whose computational cost is on the order of the number of dictionary entries. Given an alphabet, it can efficiently generate r -permutations that also satisfy a predefined set of conditions (e.g., click-order heuristics). This method is more efficient than generating all possible r -permutations from the alphabet and then checking which ones satisfy a predefined condition. Note that each r -permutation is a single ordered arrangement of r points, and that we use the term “all possible

r -permutations” to describe all possible ordered arrangements of r points.

Our methods are substantially more successful than previous purely automated attacks. Tested on the field study database of Thorpe et al. [31], some of our dictionaries find 19-83% as many passwords as human-seeded attacks (when based on independent probabilities), with only about 3% as many dictionary entries.

Our contributions include the best purely automated attacks to date against PassPoints-style graphical passwords, an evaluation of how the model of Itti et al. [16] relates to user-selected click-based graphical passwords, an efficient heuristic dictionary generation algorithm, and a new spatial clustering algorithm for grouping nearby click-points. We found that a “lazy” approach to click-order patterns (e.g., loosening the definition of a line to five points lying within some tolerance of a line) produced a substantially more successful automated attack than previous methods with comparable dictionary sizes and images [31], [10]. A click-order pattern based only on locality (all five points being near one another) was also very successful. We show how some click-order pattern dictionaries can be further optimized by applying distance constraints. Furthermore, we were able to improve these click-order pattern dictionaries using Itti’s model, producing dictionaries whose relative guessing accuracy is better than human-seeded attacks based on independent probabilities [32]. These results show that purely automated attacks pose a significant threat to PassPoints-style graphical passwords.

The remainder of this paper proceeds as follows. Section II describes related work and Section III discusses background and terminology, including computational models of visual attention. We describe purely automated attack generation methods in Section IV, results in Section V, and a discussion with concluding remarks in Section VI.

II. RELATED WORK

Many graphical passwords schemes have been proposed to date, and several surveys are available [29], [21], [26]. Here we concentrate on click-based graphical password schemes, wherein a user clicks on a set of points on one or more presented background images, and work related to guessing attacks on graphical passwords.

In *V-go* [25], users click on a sequence of predefined objects in the picture. In Blonder’s proposal [1], users click on a set of predefined tap regions. Jansen et al. [17] propose a variation, which requires users to click an ordered sequence of visible squares imposed on a background image; the squares are intended to help users repeat click-points in subsequent logins.

PassPoints [35], [37], [36] allows users to click a sequence of r points anywhere on an image while allowing a degree of error tolerance; studies using $r = 5$ suggest promising usability [36], [35], [37], [5]. A related commercial system designed for the Pocket PC, called *VisKey*, allows the user to choose the number of click-points and to set the error tolerance.

The security of click-based graphical passwords has been examined [10], [31], [28], [32]; for security analyses of other

types of graphical schemes see also Davis et al. [9] and van Oorschot et al. [33]. One way that an attacker could predict hot-spots is by using image processing tools to locate areas of interest. Dirik et al. [10] use an image processing tool for guessing PassPoints passwords to guess single-session user passwords for two images, one being a particularly simple image. For the other image, their method guessed 8% of passwords using an attack dictionary with 2^{32} entries where the full space was 2^{40} entries. In other work, Thorpe et al. [31] examine an automated method (based on a variation of Itti et al.’s [16] model of visual attention), guessing 9.1% and 0.9% of passwords on two images, using an attack dictionary with 2^{35} entries compared to a full password space of 2^{43} passwords. The method of Thorpe et al. [31] focused only on a variation of stage 1 of the model (see Section III-A), ordering an attack dictionary based on the raw values of the resulting saliency map, whereas the present paper uses the entire model including stage 2 of the model. In a preliminary version of the present work, Salehi-Abari et al. [28] guess 8-15% of passwords for two representative images using dictionaries of less than $2^{24.6}$ entries, and about 16% of passwords on each of these images using dictionaries of less than $2^{31.4}$ entries, where the full space is 2^{43} .

Basic click-order patterns were first introduced and evaluated in combination with human-seeded attacks [31], [30]; the only pattern in common with the present work is regular DIAG (i.e., without any “laziness” relaxation). Chiasson et al. [3] analyze a set of patterns for three click-based graphical password schemes: PassPoints [35], [37], [36], and two variants named Cued Click-Points (CCP) [6] and Persuasive Cued Click-Points (PCCP) [2]. In CCP and PCCP, a user clicks on a single point on each of five images, where each image (except the first image) is dependent on the previous click-point. They show that the design of the interface impacts whether users select click-points in some predictable patterns, and implied that such patterns in user choice might reduce the effective password space. The present paper mathematically models click-order patterns and uses them to mount purely automated attacks, demonstrating and experimentally quantifying the degree to which certain patterns can be used to efficiently search the password space.

Thorpe et al. [31], [32] introduce human-seeded attacks and demonstrate their efficacy against Passpoints-style graphical passwords. Human-computed data sets (harvesting click-points from a small set of users) were used in two human-seeded attacks against passwords from a field study on two different images: one based on a first-order Markov model [32], another based on an independent probability model [31]. Using their human-computed data sets (harvested from a single-session lab study), a dictionary based on independent probabilities contained $2^{31.1} - 2^{33.4}$ entries and found 20-36% of field study passwords, and a dictionary based on the first-order Markov model found 4-10% of field study passwords within 100 guesses. These attacks require the attacker to collect sufficient click-points for each image, and are image dependent, thus requiring per-image costs for systems with multiple images.

III. BACKGROUND

Our original idea was that users will tend to choose the points that compose their click-based graphical password based on the order in which the points draw their visual attention. Thus, computational models of visual attention may help identify more probable click-points. As our attacks are motivated by this idea and a subset of them use computational models of visual attention, we provide some background on models of visual attention in Section III-A. Other terminology is presented in Section III-B.

A. Models of Visual Attention

Computational models of bottom-up visual attention are normally defined by features of a digital image, such as intensity, color, and orientation [16], [15]. Feature maps are then created and used to generate a *saliency map*, which is a grayscale image where higher-intensity locations define more conspicuous areas.

Computational models of top-down visual attention can be defined by training [23]. The difficulty of these models is that the top-down task must be pre-defined (e.g., find all people in the image), and then a corpus of images that are tagged with the areas containing the subject to find (e.g., people) must be used for training. Navalpakkam et al. [22] discuss an alternate method to create a top-down model, based on *guided search* [38], which weighs visual feature maps according to the top-down task. For example, with a task of locating a red object, a red-sensitive feature map would gain more weight, giving it a higher value in the resulting saliency map. In both cases, assumptions regarding what sort of objects people are looking for are required to create such a model.

In this work, we focus on bottom-up visual attention, using the computational model of visual attention of Itti et al. [16]. We chose this model as it is well-known, and there is empirical evidence that it captures people’s bottom-up visual attention [24]. The general idea is that areas of an image will be *salient* (or visually “stand out”) when they differ from their surroundings. Given an input image, Itti’s model outputs a focus-of-attention *scan-path* to model the locations and the order in which a human might automatically and unconsciously attend these parts of the image. The model first constructs a saliency map based on visual features. Then it uses a winner-take-all neural network with inhibition of return to define a specific focus-of-attention scan-path, intended to represent the order in which a user would scan the image.

In stage 1, the saliency map is created by decomposing the original image into a set of 50 multi-level “feature maps”, which extract spatial discontinuities based on color opponency (either red-green or blue-yellow), intensity, or orientation. Each level defines a different size of the center and its surround, in order to account for conspicuous locations of various sizes. All feature maps are then combined into a single saliency map.

In stage 2, the neural network detects the point of highest salience (as indicated by the intensity value of the saliency map), and draws the focus of attention towards this location. Once an area has been attended to, inhibition of return will

prevent the area from being the focus again for a period of time. Together, the neural network with inhibition of return produces output in the form of spatio-temporal attentional scan-paths, which follow the order of decreasing saliency as defined by stage 1. Two different normalization types (producing different scan-paths) can be used with the model: *LocalMax* and *Iterative* (cf. Figure 1). In *LocalMax* normalization, the neural network will have a bias towards those areas that are closer to the previously attended location. In *Iterative* normalization, the neural network will find the next most salient area that has not been inhibited. We use *LocalMax* herein (*Iterative* was found to have inferior performance [28]).

B. Terminology and Identifying Distinguishable Points

Our overall method is based on the hypothesis that users are more likely to choose passwords consisting of click-points, each of which is a *distinguishable point*, defined as a point on a digital image that can be easily distinguished and located again by a user – e.g., by using *referenceable* points on the image (such as a corner), or *calculable* points based on other referenceable parts of the image (such as object centers). Thorpe et al. [31] used corner detection to find referenceable points, and Dirik et al. [10] used centroids to find calculable points. We use both approaches to define a *distinguishable points map* δ , as detailed below.

Regarding additional terminology, suppose that a user chooses a click-point c as part of a password. The *tolerable error* or *tolerance* t is the error allowed (in vertical and horizontal directions) for a click-point entered on a subsequent login to be accepted as c . This defines a *tolerance region* (*T-region*) centered on c . For an implementation using $t = 9$ pixels, the T-region is a 19×19 pixel square, matching the dataset [31], used herein for evaluation and comparison.

A *window cluster* is a square region of $n \times n$ pixels for some positive integer n . A *cluster* is a set of one or more points that lie within a window cluster. The geometric center of a window cluster is used as the representative of all the points within the window cluster. An *alphabet* is a set of window centers.

Corner Detection. A *corner* is defined as the intersection of two edges, where an *edge* is defined by the points in a digital image where there are sharp changes in intensity [12]. We use Harris corner detection [13] as implemented by Kovese [18]. This first identifies the edges. Those edges are then blurred to reduce the effect of any noise. Next, based on the edges, an *energy map* is generated, containing local maxima and minima. A local maximum indicates the presence of a corner. We use the recommended parameters $\sigma = 1$, $\theta = 1000$ and $r = 3$, where σ is the standard deviation of a smoothing Gaussian filter, θ is a threshold for the maximum number of corners, and r is an inhibition radius, measured in pixels around a detected corner. Figure 2 shows the *pool* image where each detected corner is illustrated by a ‘+’.

We also create a *binary corners map* (a specialized type of *binary map* or one-to-one mapping from its pixels of value 0 or 1 to the pixels of the original image): when a pixel is a corner in the original image, its corresponding value is 1; otherwise 0.

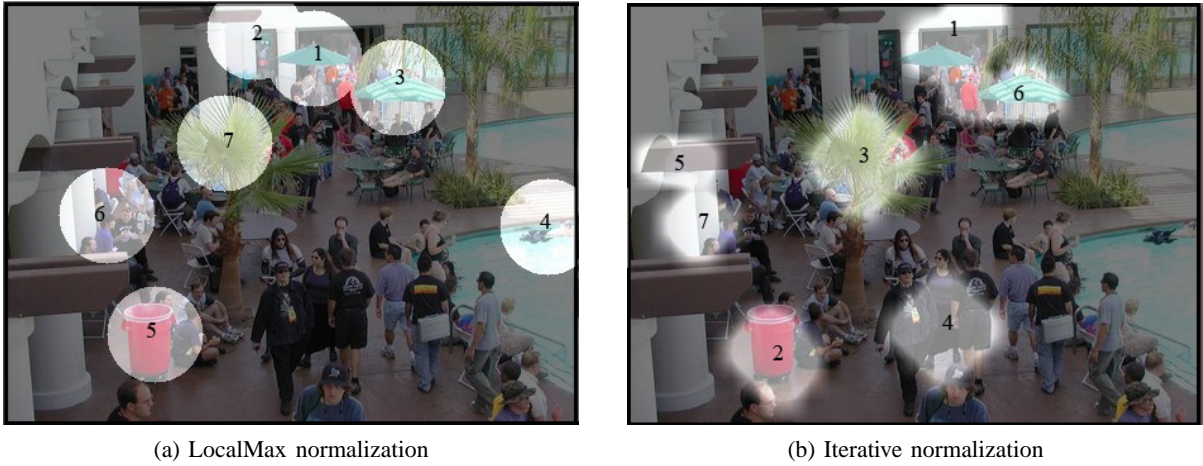


Fig. 1. *pool* image (unmodified version from [35], [37]) with the first 7 steps in the scan-path.

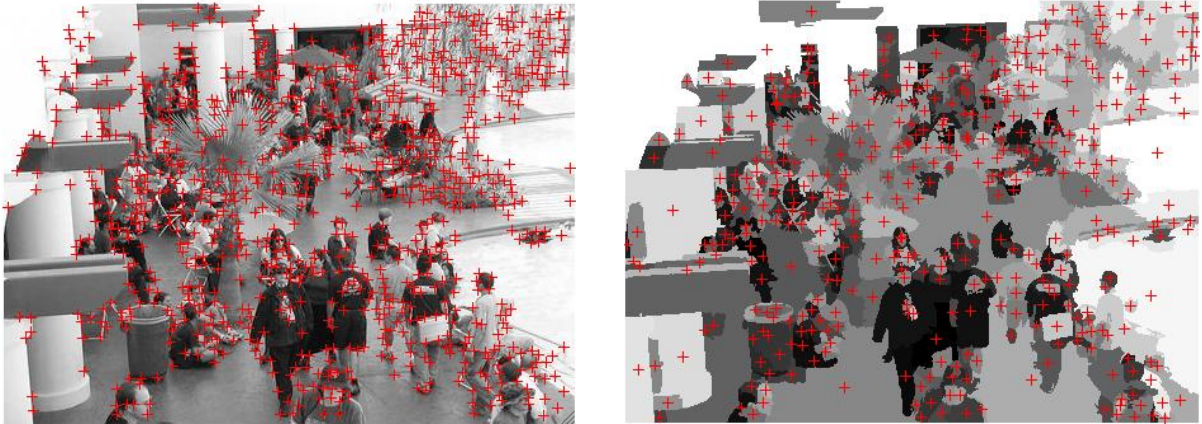


Fig. 2. Corner detection (left) and center detection (right) for *pool* image.

Centroid Detection. To find the centers of objects, we first partition the digital image into segments using *image segmentation*, by the mean-shift segmentation algorithm [7], which takes a feature (range) bandwidth, spatial bandwidth, and a minimum region area (in pixels) as input. We set these parameters to 7, 9, and 50 respectively, which we found empirically to provide an acceptable segmentation with the smallest resulting number of segments.

After segmentation, we calculate the center (X_S, Y_S) of each segment (centroid) S from the arithmetic mean of each coordinate of the segment’s points: $X_S = \frac{1}{n(S)} \sum_{i \in S} x_i$ and $Y_S = \frac{1}{n(S)} \sum_{i \in S} y_i$. Here x_i and y_i are pixel coordinates, and $n(S)$ denotes the total number of pixels in segment S . The x coordinates of all points in S are involved in calculating X_S , not only those along the maximum width.

Figure 2 (right) illustrates the resulting segments of the *pool* image. The center of each segment is denoted by a ‘+’. We also create a *centers map*, which is a binary map of the same size as the original image. If a pixel is a center of a segment in the corresponding image, its value is 1 in the centers map; otherwise 0. Our *distinguishable points map* δ is the binary map that is the logical (inclusive) “or” of the binary centers map and binary corners map.

IV. EXPERIMENTAL METHODOLOGY

Our attack methods are motivated by the following conjectures related to user choice. Regardless of the degree to which these conjectures are true, they have led us to significantly improved attack algorithms, which is our objective herein, rather than proving or disproving these conjectures per se.

Conjecture 1 *Users are likely to collectively prefer some areas of an image more than others, with the aggregate effect that a significant subset of users will choose passwords composed of click-points that are among the collectively preferred click-points.*

Conjecture 2 *Points that are collectively preferred can be identified by image processing tools (e.g., models of visual attention).*

Another factor that could influence the complexity (and thus a user’s preference) of a password is the relationship between click-points that compose a password. People are better at recalling fewer pieces of visual information [8], motivating Conjecture 3.

Conjecture 3 *A significant subset of users are likely to choose sets of points that can be grouped, e.g., by following one of a set of simple click-order patterns (such as left to right).*

Conjectures 1, 2, and 3 lead us to pursue attacks that use click-order patterns and image processing methods to create efficient, ordered attack sub-dictionaries. Some of our dictionaries use a *window clustering* algorithm, described in Section IV-A, to represent a set of click-points in a more compact way. We describe our attack alphabets in Section IV-B; one is based on image processing methods. To generate an attack dictionary based on heuristics (in our case these being click-order patterns), we introduce a general graph-based algorithm in Section IV-C. We describe specific click-order patterns and their specification in Section IV-D.

A. Window Clustering Algorithm

We assume that an attacker’s goal is to guess the largest number of passwords with the fewest guesses. After creating a set of points for a guessing alphabet (which might be used in passwords in any ordering of five clicks), those within the same tolerance region could be redundant (effectively guessing the same point). We use the term *clustering* to mean normalizing a set of points to a single value. The intuition behind clustering is that given the system error tolerance, one point would be accepted as a correct entry for all others within its tolerance region.

We introduce a clustering algorithm (*window clustering*), based on setting a window of fixed size (not necessarily the same size as the tolerance region) over the largest number of points it can cover. We then replace those candidate points inside the window with the geometric *center* of the window. Thus, the center of the cluster is not necessarily one of the original input points (in contrast to a previous clustering algorithm [31]).

More precisely, window clustering is a greedy algorithm with a fixed window size. Starting with all candidate points, find the next position for the window that covers the maximum number of remaining points (ties are broken arbitrarily). Then store the center of the window to represent the points in the window, and erase the corresponding points. Continue this process until no candidate points remain. The candidate points we use are the points with value 1 in B_i of Section IV-B1, and the window size is set to 19×19 .

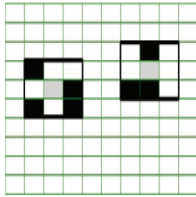


Fig. 3. Window clustering.

Figure 3 shows an example set of candidate points with black squares, where each square represents a pixel. These 7 candidate points are covered with two 3×3 windows and will be represented by the centers of the two windows illustrated with grey squares.

B. Attack Alphabets

Motivated by Conjectures 1 and 2, we introduce a set of alphabets based on Itti’s computational model of bottom-up visual attention that we call *VA*, introduced in Section IV-B1. For comparison, we introduce an alphabet in Section IV-B2 that covers the entire image.

1) *Visual-Attention Based Alphabet (VA)*: We used the Saliency Toolbox [34] implemented in Matlab. The weights of all feature maps used by the toolbox are set to one, which assigns orientation, intensity and colors the same level of importance. Normalization type is set as *LocalMax* and for all other settings, we use their default. With the resulting scan-path, we generate an ordered set of alphabets for use in a guessing attack as described in the paragraphs below. We generate a map of candidate click-points using the distinguishable points map δ as a bitmask to the resulting attracted regions of the image (i.e., using a logical “and”). We then refine this binary map of candidate points by using the window clustering algorithm of Section IV-A.

In this way, we generate a set of binary maps S' , whose n elements represent the cumulative n steps in the scan-path (element i contains all steps from the first to the i^{th} step). More specifically, the i^{th} element in S' is the binary map B_i , which is generated from all scan-path steps up to step i : $S' = \{B_1, B_2, \dots, B_n\}$ where $B_i = A_1 \vee A_2 \vee \dots \vee A_i$ and each element A_j is a binary map representing the j^{th} step in the scan-path. In other words, $B_i = B_{i-1} \vee A_i$ and $B_1 = A_1$. Note that each element A_j contains many pixels of value 1, for example in Figure 1a, A_7 would include *all* highlighted pixels within the circle labeled 7. Next, we calculate $\{C_1, C_2, \dots, C_n\}$ where $C_i = B_i \wedge \delta$, the intersection (logical “and”) of each element B_i with δ , and run the window clustering algorithm on each C_i to produce D_i , the resulting set of cluster centers (which are pixel locations on the image). The final set of attack alphabets $VA = \{D_1, D_2, \dots, D_n\}$ is ordered by the number of scan-path steps it includes.

The *VA* set of alphabets uses the scan-path to prioritize the dictionary entries; the first alphabet uses only the first scan-path element, the second alphabet uses both the first and second scan-path elements, etc. The order of each alphabet within *VA* is motivated by the intuition that users may choose their click-points based on points that are in the focus-of-attention scan-path – but not necessarily in the order of the scan-path. For example, users may choose click-points according to a click-order pattern.

We use *VA* to create a dictionary motivated by Conjectures 1 and 2, and call it *VA-H*, where heuristic H denotes a specific click-order pattern. The attack sub-dictionary Z_i , of 5-permutations of the elements of D_i that satisfy a heuristic H , is generated by the dictionary generation algorithm explained in Section IV-C. The final attack dictionary set $Z = \{Z_1, Z_2, \dots, Z_n\}$ is ordered by the number of steps in the scan-path that are considered, e.g., all passwords from dictionary Z_2 are tried as candidate passwords only after those in Z_1 are exhausted.

2) *Alpha Alphabet (α)*: To examine the efficacy of attack dictionaries based on click-order pattern heuristics alone (i.e., without additional image processing methods as in *VA*), we

also used the following alphabet α with click-order patterns to generate dictionaries. α is the set of pixels each of which is a window center, upon partitioning an image into T-regions by placing a grid of 19×19 windows (i.e., the same size as the T-region) over the image; see Figure 4. Note that the T-region used in creating α depends only on the system error tolerance, independent of the parameter τ used later in different relaxation modes.



Fig. 4. Each ‘+’ represents a character in the alphabet (α).

C. Dictionary Generation Algorithm

Suppose an attacker plans to generate a dictionary consisting of the subset of all possible r -permutations (of a specific alphabet A), where the elements of the subset must also satisfy some predefined conditions (e.g., click-order patterns). One approach is to generate all possible r -permutations of A and then keep only those which fulfill the predefined conditions (heuristics). In this approach, assuming the heuristic check is constant-time, the time complexity of dictionary generation, Θ_A , is $O(\frac{n!}{(n-r)!})$, where $n = |A|$. Note that the dictionary cardinality, Θ_D , can be significantly smaller than Θ_A ($\Theta_D \ll \Theta_A$), depending on the predefined conditions.

Instead we present a graph-based algorithm for dictionary generation whose computational cost is equal to the number of dictionary entries ($\Theta_D = \Theta_A$). At a high-level, this efficiency is achieved by creating a graph that captures only those elements that fulfill the predefined heuristic, where all paths of length $r - 1$ are output as passwords. For heuristics corresponding to a small portion of the password space, this is much more efficient than iterating through the entire password space. We first partition each condition (heuristic) into a number of sub-conditions (sub-heuristics). Define each sub-heuristic h in the form of a binary relation R_h on the set A , i.e., a subset of $A \times A$ [27]. Thus, $R_h \subseteq A \times A$. Given $(a, b) \in R_h$, both a and b belong to A and this ordered pair satisfies h . We represent each relation R_h by a matrix M_h with entries

$$M_h(i, j) = \begin{cases} 1 & \text{if } (a_i, a_j) \in R_h \\ 0 & \text{if } (a_i, a_j) \notin R_h \end{cases}$$

where $A = \{a_1, \dots, a_n\}$. M_h can be represented by a digraph G_h with vertices corresponding to the indices i of a_i and edge $\langle i, j \rangle$ from i to j if and only if $M_h(i, j) = 1$.

To generate the sub-dictionary D_h whose entries satisfy the sub-heuristic h and are also r -permutations of elements in A , we find all paths of length $r - 1$ in the graph G_h , using

Algorithm 1. A path source can be any node of G_h . A path of length $r - 1$, which is one of the r -permutations of A , is represented by $p = \langle i_1, i_2, \dots, i_r \rangle$.

Algorithm 1

```

GenerateDictionary ( $G_h, r$ )
%  $G_h$  is a digraph with vertices 1 to  $n = |A|$ .
 $D_h \leftarrow \emptyset$ 
for  $i = 1$  to  $n$ 
     $paths \leftarrow \text{FindPaths}(i, G_h, r - 1)$ 
    %  $paths$  is a set of paths of length  $r - 1$  (i.e., passwords).
     $D_h \leftarrow D_h \cup paths$ 
end for
return  $D_h$ 

```

$\text{FindPaths}(source, G, l)$ is a recursive function which finds all paths of length l from node $source$ in digraph G ; see Algorithm 2. It finds paths of length $l - 1$ for all neighbors of $source$ and then prepends $source$ to those paths.¹ For the base case of a path of length one, each path includes the source and one neighbor. Algorithm 1 generates a sub-dictionary for a sub-heuristic, such as a right-to-left and bottom-to-top (*RL_BT*) click-order pattern, which is a sub-heuristic of the *DIAG* pattern heuristic (see Section IV-D). The union of the sub-dictionaries is the final attack dictionary.

Algorithm 2

```

FindPaths( $source, G, l$ )
 $S \leftarrow \emptyset$ 
% Upon termination,  $S$  is a set of paths of length  $l$ .
for all nodes  $i \in \text{Neighbors}(source)$ 
    %  $\text{Neighbors}(i)$  = set of neighbors of node  $i$ .
    if  $l > 1$  then
         $paths \leftarrow \text{FindPaths}(i, G, l - 1)$ 
        for all  $p \in paths$  do
             $p \leftarrow \text{Prepend}(source, p)$ 
            %  $\text{Prepend}(i, p)$  prepends node  $i$  to path  $p$ .
        end for
    else
         $paths \leftarrow \{ \langle source, i \rangle \}$ 
    end if
     $S \leftarrow S \cup paths$ 
end for
return  $S$ 

```

The actual dictionary creation time for attacks depends on the number of dictionary entries, the relation used (e.g., *DIAG*), and the properties of the resulting G_h . In practice, our dictionary creation times for all of our dictionaries were on the order of hours, rather than weeks, on a 1.83-GHz Dell Inspiron Intel Core 2 with 2 GB RAM.

D. Click-order Patterns, Relaxation and Constraints

We examine three click-order patterns alone (*DIAG*, *LINE*, and *Localized Omni-Direction*), and with what we call *lazy*

¹While a recursive version of *FindPaths* is presented here for conceptual simplicity, an iterative version is used in practice.

and *super-lazy* variations (for both DIAG and LINE) that relax the definition of the patterns. DIAG includes any sequence of 5 click-points that follow *both* a consistent vertical and horizontal direction (e.g., straight lines in any direction, most arcs, and step-patterns); LINE includes any sequence of 5 click-points that follow either a vertical or horizontal line (see Fig. 5). Localized Omni-Direction includes all sequences of 5 click-points in which each two consecutive points are constrained by only a predefined distance constraint (but not by direction).

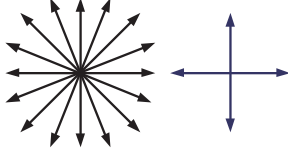


Fig. 5. Directions included by DIAG (left) vs. LINE (right).

We break down the DIAG heuristic into four sub-heuristics LR_TB , LR_BT , RL_TB and RL_BT based on the mnemonics: LR (left-to-right), RL (right-to-left), TB (top-to-bottom), BT (bottom-to-top). More specifically, the defining relations for the DIAG heuristic are ($\tau \geq 0$ is a relaxation parameter, described further below):

$$\begin{aligned} R_{LR_BT} &= \{(P_i, P_j) \mid x_i \leq x_j + \tau \text{ AND} \\ &\quad y_i \geq y_j - \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \\ R_{RL_BT} &= \{(P_i, P_j) \mid x_i \geq x_j - \tau \text{ AND} \\ &\quad y_i \geq y_j - \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \\ R_{LR_TB} &= \{(P_i, P_j) \mid x_i \leq x_j + \tau \text{ AND} \\ &\quad y_i \leq y_j + \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \\ R_{RL_TB} &= \{(P_i, P_j) \mid x_i \geq x_j - \tau \text{ AND} \\ &\quad y_i \leq y_j + \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \end{aligned}$$

where $P_i = (x_i, y_i)$ and $P_j = (x_j, y_j)$ are two independent (not necessarily successive) points, and the alphabet is $A = \{P_1, P_2, \dots, P_n\}$. By convention, the positive y axis extends downward from the top-left pixel of the image. $D_E(P_i, P_j) = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$ is the Euclidean distance between P_i and P_j .

Having observed some users choose successive click-points within a bounded distance from the previous click-point motivated us to define a distance constraint threshold T_d for consecutive points in LINE and DIAG ($T_d = \infty$ removes the constraint). When $T_d \neq \infty$, we subscript the dictionary with T_d .

As noted earlier, the DIAG heuristic has four sub-heuristics and thus separate graphs. For each, we generate a sub-dictionary using Algorithm 1. The DIAG dictionary is the union of four sets of passwords: $D_{DIAG} = D_{LR_TB} \cup D_{LR_BT} \cup D_{RL_TB} \cup D_{RL_BT}$. Similarly, $D_{LINE} = D_{LR} \cup D_{RL} \cup D_{BT} \cup D_{TB}$, where the four sub-dictionaries in LINE are generated using the defining relations:

$$\begin{aligned} R_{LR} &= \{(P_i, P_j) \mid (x_i \leq x_j + \tau) \text{ AND} \\ &\quad |y_i - y_j| \leq \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \\ R_{RL} &= \{(P_i, P_j) \mid (x_i \geq x_j - \tau) \text{ AND} \\ &\quad |y_i - y_j| \leq \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \\ R_{BT} &= \{(P_i, P_j) \mid (y_i \geq y_j - \tau) \text{ AND} \end{aligned}$$

$$\begin{aligned} R_{TB} &= \{(P_i, P_j) \mid (y_i \leq y_j + \tau) \text{ AND} \\ &\quad |x_i - x_j| \leq \tau \text{ AND } D_E(P_i, P_j) \leq T_d\} \end{aligned}$$

For LINE and DIAG, the allowance $\tau \geq 0$ serves to relax the pattern, motivated as follows. Although the user might be inclined to select points along a line, the elements of that line may be influenced by which click-points the user otherwise prefers. In the absence of linear structures in the underlying image, the collection of four line segments, obtained by connecting successive pairs of user-selected click-points, may only approximate a line. Therefore, two variations on both DIAG and LINE allow “lazier” lines (see Figure 6): “lazy” uses $\tau = 19$ and “super-lazy” uses $\tau = 28$. Our default relaxation value is $\tau = 9$ pixels (equal to the system tolerance t). We denote a dictionary using a lazy or super-lazy τ with superscripts $+$ and $++$ respectively.

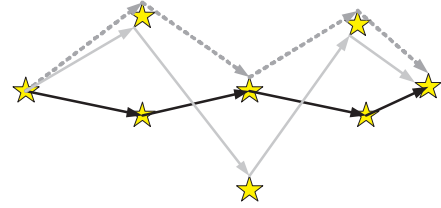


Fig. 6. Laziness modes: normal (black), lazy (dashed grey), and super-lazy (solid grey).

A Localized Omni-Direction (LOD) dictionary is generated based on the single defining relation $R_{LOD} = \{(P_i, P_j) \mid |x_i - x_j| \leq \tau \text{ AND } |y_i - y_j| \leq \tau\}$. Here τ serves as the distance constraint parameter on the two alphabet points P_i and P_j . Using Algorithm 1, we generate the corresponding dictionary denoted LOD^x , where $x = \tau$.

V. EXPERIMENTAL RESULTS

We examine each click-order pattern (DIAG, LINE, and LOD) with each of the attack alphabets described in Section IV-B.² To evaluate each click-order pattern independent of visual attention models, we use the α alphabet; to evaluate the effect of using a visual attention model, we use the VA set of alphabets. To allow comparison, we tested these methods by trying to guess user passwords from a previous PassPoints field study dataset [31], [5]. The study was 7-weeks or longer (depending on the user), involving 223 user accounts on a web-based implementation of PassPoints allowing access to course notes, assignment solutions, and tutorials. We focus on the field study rather than the related lab study for increased ecological validity of the passwords’ long-term memorability. Participants were from two first year courses for computer science students, and a first year course for non-computer science students enrolled in a science degree. Participants used one of two background images, *pool* or *cars* (see Figure 7), preselected to be representative of highly detailed usable images at 451×331 pixels.

²This corrects preliminary results reported earlier [28] (some dictionary sizes are up to one bit larger, and some attack efficacies are slightly improved).



Fig. 7. *cars* (originally from [14]). See Figure 1 for *pool*.

Passwords had 5 click-points, no two within $t = 9$ pixels of another (vertically and horizontally). Thus, the size of the resulting password space is about 2^{43} . Consistent with the previous study, we used only the final passwords exercised by each user (and recalled at least once). These 223 user accounts mapped to 189 distinct users (34 users were in two classes; all but one of them were assigned a different image for each account). Overall, 114 user accounts used *pool* and 109 used *cars* as a background image. Previous work on this data set provides images and details showing the distribution of user click-points [31].

A. DIAG Results

We first examine the DIAG pattern using the α alphabet, with all laziness modes (see Table I). The results for the dictionaries marked ‘+’ and ‘++’ are the same because the T-regions are non-overlapping, and the difference between $\tau = 19$ and 28 is 9, which is not greater than τ and thus does not include any more T-regions (the same is true for Table II).

TABLE I
RESULTS FOR DIAG CLICK-ORDER HEURISTIC.

Dictionary	Entries	% guessed	
		<i>pool</i>	<i>cars</i>
$\alpha DIAG$	$2^{33.02}$	21.1%	27.5%
$\alpha DIAG^+, \alpha DIAG^{++}$	$2^{35.26}$	48.2%	54.1%

Table I reports that the $\alpha DIAG^+$ dictionary guesses 48% of passwords for *pool* and 54% of passwords for *cars* with dictionaries of approximately 2^{35} entries; these results do not involve use of any visual attention modeling. Previous purely automated attacks [31] on the same password database, with a dictionary of 2^{35} entries, guessed 9.1% (*cars*) and 0.9% (*pool*).

We also combine *VA* with the DIAG click-order patterns at all laziness modes. The cumulative distribution function (CDF) of results (until each dictionary is exhausted) are provided in Figure 8. This creates what might be viewed as a more efficient dictionary: for $DIAG^{++}$ finding 15.8-18.3% of passwords using dictionaries of less than 2^{32} entries, i.e., finding nearly $\frac{1}{3}$ as many as the $\alpha DIAG^{++}$ dictionary, with almost 10 times fewer entries.

B. LINE Results

Table II provide results for the LINE pattern using the α alphabet. $\alpha LINE^+$ finds 23.7% of passwords for *pool*, and 52.3% for *cars* using a dictionary of 2^{29} entries. Using $\alpha LINE^+$ (vs. $\alpha DIAG^+$), the percentage found drops only minorly from 54% to 52% for *cars* and from 48% to 24% for *pool* (still about half as many), despite a dictionary about 75 times smaller. Thus for both images, $\alpha LINE^+$ is more efficient (in terms of efficacy relative to dictionary size) than any variation of DIAG. This might, in retrospect, be less surprising for *cars*, given the line structures in the orientation of the cars, than for *pool*.

TABLE II
RESULTS FOR LINE CLICK-ORDER HEURISTIC.

Dictionary	Entries	% guessed	
		<i>pool</i>	<i>cars</i>
$\alpha LINE$	$2^{20.88}$	3.5%	22.0%
$\alpha LINE^+, \alpha LINE^{++}$	$2^{29.02}$	23.7%	52.3%

We also combine *VA* with the LINE patterns. The cumulative distribution function (until each dictionary is exhausted) is provided in Figure 9. As with the DIAG pattern, the *VA* alphabet creates a more efficient dictionary relative to its size. The $LINE^{++}$ variation guesses 7.0-16.5% of passwords using a dictionary of less than $2^{26.2}$ entries, finding $\frac{1}{4}$ to $\frac{1}{3}$ as many passwords as $\alpha LINE^{++}$ with a dictionary 7 times smaller.

For all click-order patterns, dictionaries composed from the *VA* alphabet work better on *cars* than *pool*. This is at least partially because corner and center detection does not work as well on *pool* as on *cars*.

C. Localized Omni-Direction Results (LOD)

We tested the LOD pattern using alphabets *VA* and α , with distance constraints $T_d = 20, 40, 60, 80,$ and 100 pixels.

First we generated dictionaries using α and tested on the above-mentioned dataset. Table III and Figure 10 show that the *LOD* pattern is comparable to $\alpha DIAG^+$ for *pool*. αLOD^{100} has 2^{35} entries and finds 47.4% of passwords on *pool*, whereas $\alpha DIAG^+$ (Section V-A) found a comparable number of passwords on *pool* with essentially the same sized dictionary. For this dataset, $\alpha LINE^+$ (Section V-B) remains the best attack strategy for *cars*.

Next we generated LOD^{100} dictionaries using *VA* and tested them on the same dataset. The results (see Figure 11) showed that $VA-LOD^{100}$ found $\frac{1}{3}$ as many as αLOD^{100} , with a dictionary 8 times smaller. The $VA-LOD^{100}$ dictionary contains 2^{32} entries and found 14.0-15.6% of passwords.

D. Effect of Distance Constraint

Here we explore the impact of adding distance constraints to the DIAG and LINE pattern attacks. The *LOD* pattern, defined only by distance constraint, was described separately in Section V-C.

First we examine DIAG and LINE using the α alphabet and distance constraints $T_d = 25, 50, 75, 100, 125,$ and 150. The efficacy as a function of T_d , and for all laziness modes, is

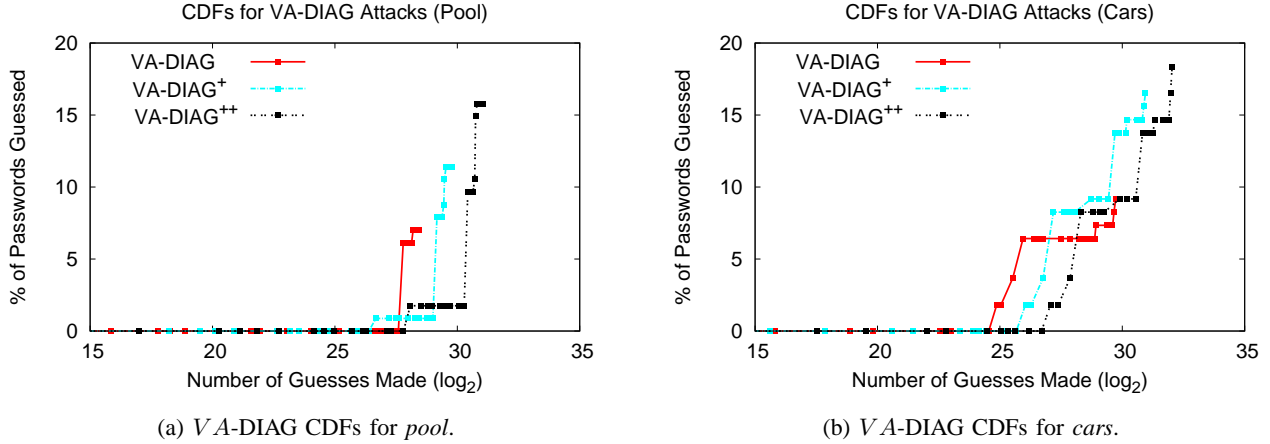


Fig. 8. CDFs for DIAG with VA.

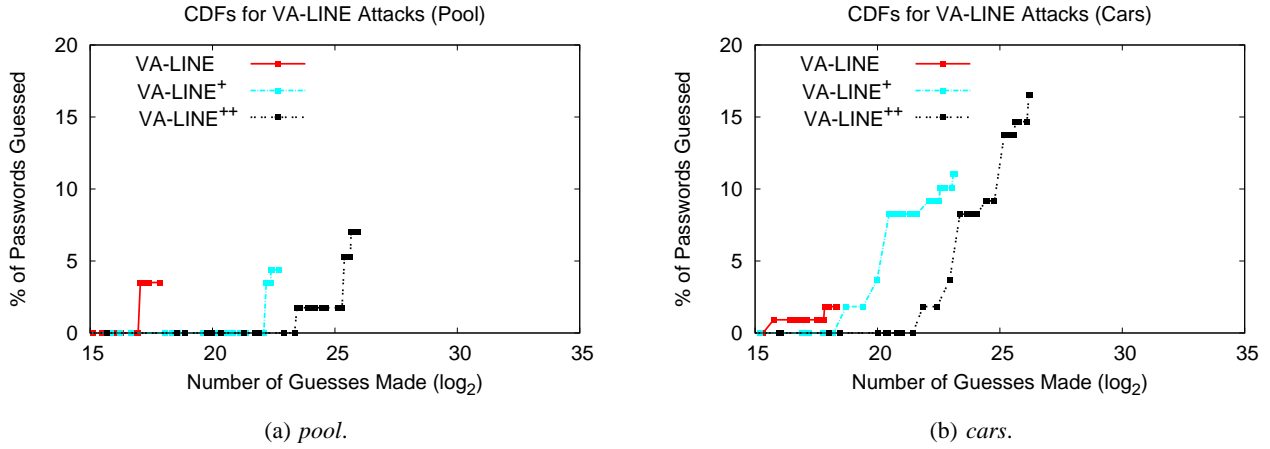


Fig. 9. VA-LINE CDFs.

TABLE III
DICTIONARY SIZES FOR α LOD ATTACKS.

Dictionary	α LOD ²⁰	α LOD ⁴⁰	α LOD ⁶⁰	α LOD ⁸⁰	α LOD ¹⁰⁰
Entries	$2^{19.61}$	$2^{26.28}$	$2^{30.19}$	$2^{32.94}$	$2^{35.02}$

provided in Figure 12. The dictionary sizes for each distance constraint and pattern is provided in Table IV.

TABLE IV
RESULTS FOR CLICK-ORDER HEURISTICS WHEN COMBINED WITH DISTANCE CONSTRAINTS.

Dictionary	Distance constraint T_d					
	25	50	75	100	125	150
α LINE _x	$2^{10.44}$	$2^{14.25}$	$2^{16.42}$	$2^{18.78}$	$2^{19.74}$	$2^{19.97}$
α LINE _x ⁺⁺	$2^{16.58}$	$2^{23.55}$	$2^{25.12}$	$2^{26.90}$	$2^{27.50}$	$2^{27.94}$
α DIAG _x	$2^{14.44}$	$2^{21.34}$	$2^{25.00}$	$2^{28.20}$	$2^{29.86}$	$2^{31.00}$
α DIAG _x ⁺⁺	$2^{15.58}$	$2^{24.65}$	$2^{27.83}$	$2^{30.66}$	$2^{32.06}$	$2^{33.07}$

In Figure 12, of course, the less restrictive the distance constraint is, the more passwords the resulting dictionary finds; however, at each distance constraint studied, the dictionary size is reduced substantially while maintaining a (proportionally) large percent of the guessing accuracy. For instance, consider

$T_d = 150$ with the α DIAG⁺⁺ dictionary, i.e., α DIAG₁₅₀⁺⁺: for *cars*, 50% of passwords are guessed (compared to 54% when no distance constraint is used) and for *pool*, 41% (compared to 48% when no distance constraint is used, i.e., $T_d = \infty$). Thus a more than 4 times smaller α DIAG₁₅₀⁺⁺ dictionary still guesses 92-85% of the passwords that α DIAG⁺⁺ does. This trend holds for each distance constraint we used, for each dictionary (LINE and DIAG with different laziness modes). This suggests that distance constraint (from smallest to largest) is an effective method for prioritizing an attack dictionary. This attack is surprisingly effective even with small distance constraints (e.g., $T_d = 50$); in particular α DIAG₅₀⁺⁺ guesses 3% and 10% of passwords on *cars* and *pool* respectively, with a dictionary of fewer than 2^{25} entries.

We next consider distance constraints with the VA-DIAG⁺⁺ dictionary. The CDFs in Figure 13 show that these same distance constraints are also effective for dictionaries

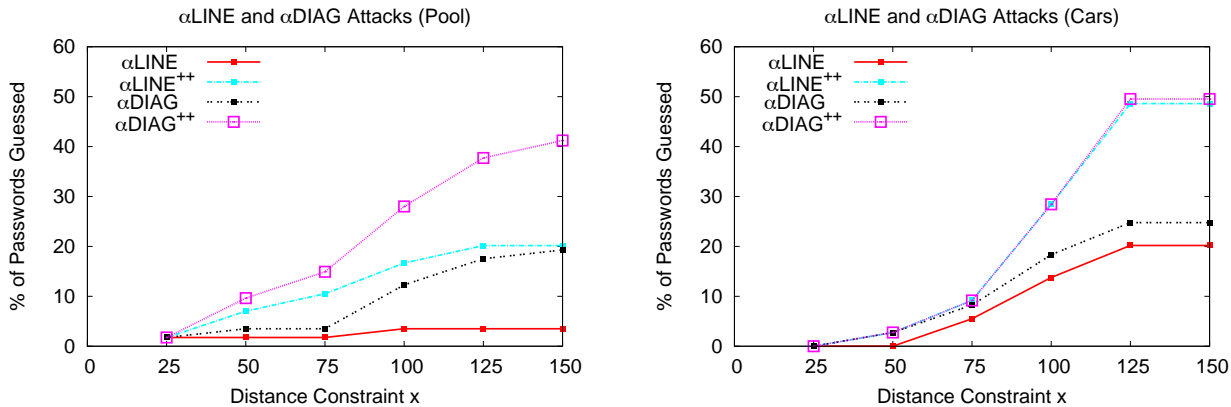


Fig. 12. Attack efficacy as a function of distance constraint $x = T_d$ (for various dictionaries).

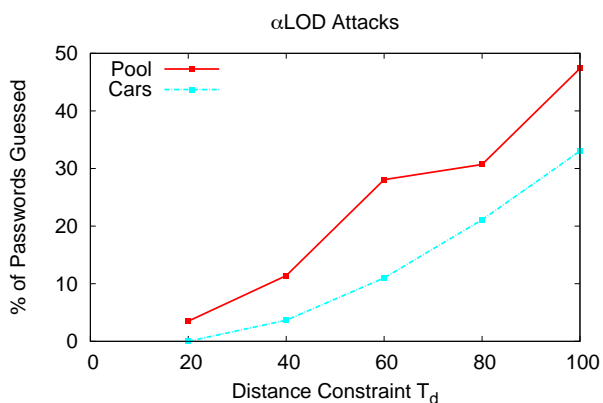


Fig. 10. α LOD attacks: passwords guessed as a function of distance constraint T_d .

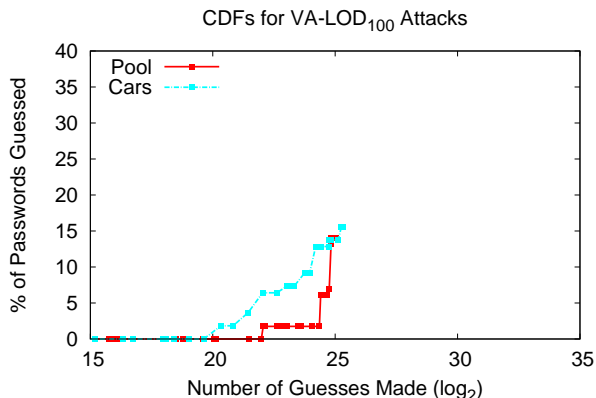


Fig. 11. CDFs of $VA-LOD^{100}$ for both *pool* and *cars*.

generated with the VA alphabet: $VA-DIAG_{125}^{++}$ guesses nearly as many passwords as $VA-DIAG_{\infty}^{++}$ (i.e., with no distance constraint), despite dictionaries 4 to 8 times smaller for both images. Also, VA -based dictionaries are more effective than those generated with α : $VA-DIAG_{125}^{++}$ is 8 times smaller than $\alpha DIAG_{125}^{++}$ and yet still guesses more than $\frac{1}{3}$ as many passwords.

E. Further Optimizations: Window Clustering Size

Our previous experiments herein used a default window size of 19×19 pixels in the window clustering algorithm. We hypothesized that smaller window sizes would introduce less error in VA (since clustering introduces some inherent information loss), increasing its effectiveness. Of course, smaller window sizes imply a larger alphabet. We re-ran the experiments for $VA-DIAG^{++}$ and $VA-LINE^{++}$ using a window size of 15×15 to see how it impacts both guessing effectiveness and dictionary size (number of guesses). The results are plotted in comparison to the default window size in Figure 14. For *pool*, the smaller window size increases the overall number of passwords found: for $VA-DIAG^{++}$, 32% vs. 16% with the larger window size. The dictionary size increases by a factor of 4. This suggests that the dictionary is less efficient relative to its size, but reducing the window size provides a viable attack continuation strategy. The results shown in Figure 14 suggest that VA (and thus Itti's model of visual attention) was more accurate for *pool* than *cars*, and in general we expect variation across images.

We expect that this is related to image processing measures working better for *cars*. Prior to applying the window clustering algorithm, our VA attacks use corner and centroid detection which both introduce some image-dependent error (E_c), which is greater for images not containing rectangular shapes (e.g., *pool*). The window clustering algorithm, through reducing the number of points, loses information and thus creates some error (E_w) dependent on the window clustering size. The overall error of our image processing methods (E_t) depends on both E_w and E_c . Since *cars* has more rectangular shapes (cars, license plates, etc.), we expect $E_c(\text{cars}) < E_c(\text{pool})$. Because $E_w(\text{cars}) = E_w(\text{pool})$, $E_t(\text{cars}) < E_t(\text{pool})$. E_t should be less than the T-region size (here, $t = 19$) to successfully guess a click-point. Reducing the clustering size decreases E_w , thus decreasing E_t . For images where E_c was large, reducing E_w may compensate enough to bring the overall error E_t below the overall error tolerance of the system (in our case $t = 19$), which increases the success rate.

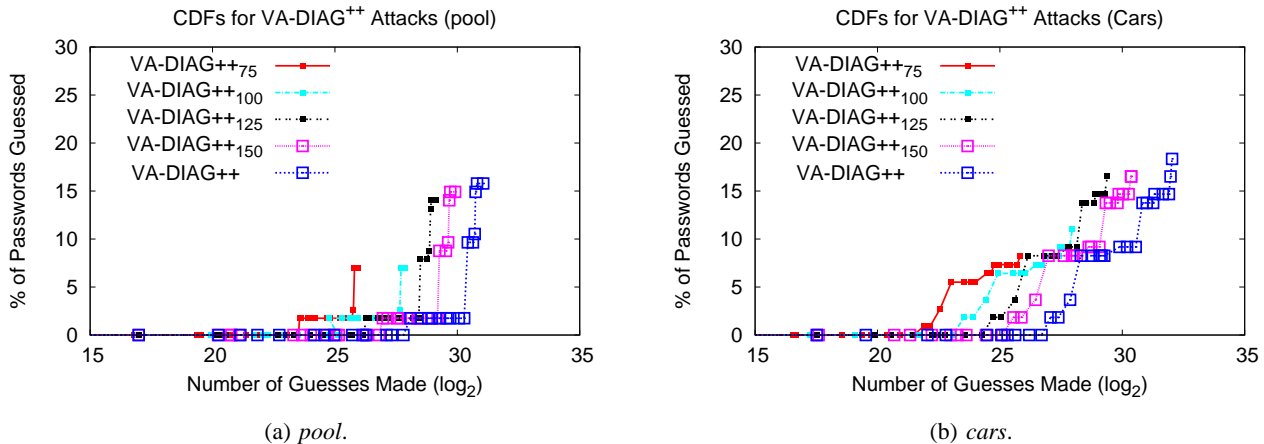


Fig. 13. VA-DIAG++ CDFs.

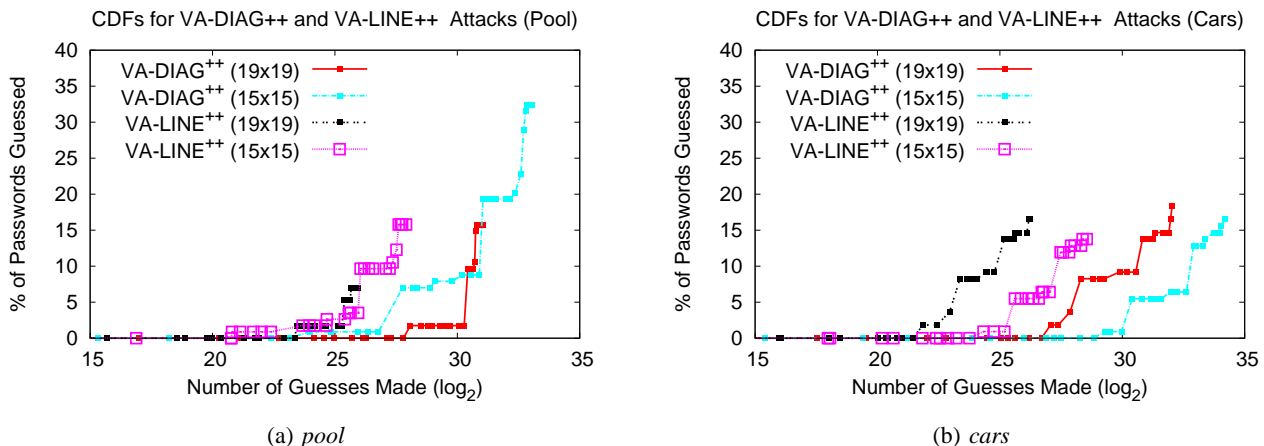


Fig. 14. CDFs for VA-DIAG++ and VA-LINE++ using different window clustering sizes.

VI. DISCUSSION AND CONCLUDING REMARKS

We provide what is to our knowledge the best automated attack against PassPoints-style graphical passwords to date. Combining click-order patterns with our laziest relaxation rule yielded highly effective dictionaries. We were able to further reduce the dictionary size while retaining some accuracy using Itti et al.’s [16] computational model of bottom-up visual attention. We also explored distance constraints to determine how effective they were at guessing passwords both alone (captured by LOD), and combined with other click order patterns (DIAG and LINE). We found that although distance constraints alone do not provide a more effective dictionary than other click-order patterns, they appear to provide a reasonable heuristic for prioritizing a dictionary (from shorter to longer distance constraints).

Our results are a significant improvement on previous work for purely automated guessing PassPoints-style graphical passwords. The dictionary that guessed the greatest percentage of passwords is *DIAG* with the laziest relaxation rule (α *DIAG*⁺⁺), finding over 48% of user passwords in our dataset for each of two images. Previous approaches found only 1-9% [31] for the same images and user study password

database, and 8% [10] for a single (comparable) image. Another notable result is that the LINE dictionary, with the laziest relaxation rule (α *LINE*⁺⁺) is less than 2% of the size of α *DIAG*⁺⁺ and still guesses 24-52% of passwords.

Although the lazy click-order dictionary sizes are not as small as previous dictionaries used for human-seeded attacks [32], when we combine them with a model of visual attention (recall Section III-A), our results are comparable to the human-seeded (independent probability) results for *cars*. Further reduction in the dictionary size can be achieved by using a distance constraint; for example, constraining the distance to 125 pixels in *DIAG* dictionaries (with the visual attention model) reduces the number of dictionary entries by 75-87%, but the efficacy only drops by 1-2%.

In all of our dictionaries using click-order patterns, a larger percentage of passwords were guessed using the α alphabet (*not* based on a visual attention model). However, using the *VA* alphabet (based on a visual attention model) provided a more efficient dictionary in that the reduction of the number of entries in the dictionary was more than the reduction in guessing accuracy; for example *VA-DIAG*⁺⁺ guessed 33% as many passwords as α *DIAG*⁺⁺ using a dictionary

with 10% of the entries. The relative “efficiency” of the $V A$ dictionaries, however, cannot be extended in their present form to guess a larger percentage of passwords, because the full dictionaries are exhausted.

These results suggest that automated attacks provide an effective alternative to a human-seeded attack against PassPoints-style graphical passwords. Furthermore, they allow continuation of an attack using click-order patterns (without any prioritization through visual attention models or other means), guessing more passwords overall than human-seeded methods. Finally, purely automated attacks are arguably much easier for an attacker to launch (removing the requirement of humans to index the images), especially if large image datasets are used. We emphasize that a number of our attack dictionaries (those composed from the α alphabet), do not rely on visual attention techniques or any image-specific pre-computation, implying that the actual dictionaries are the same for all images, though the attack results (i.e., their effectiveness) are image-dependent and of course depend also on the actual passwords chosen by any users in question. We do not expect that these attacks can be effectively applied to multi-image click-based schemes (e.g., PCCP [2]).

Our findings might be used to help background image selection, although precise details of an exact method remain unclear. As one possibility, corners and centroids of images might be extracted, and used to build a click-order heuristic graph (as in our dictionary generation algorithm); the images that generate a larger resulting dictionary might indicate a more attack-resistant image. Another possibility might be to measure the amount of structure an image has, assuming that such image structure would encourage click-order patterns.

Our overall results indicate that Itti’s model of visual attention with the parameters and implementation we used, when all possible r -permutations of points in the scan-path are considered, models a meaningful percentage (from an attacker viewpoint) of user passwords. If we assume that Itti’s model using the default settings is an accurate representation of bottom-up visual attention, our results are consistent with bottom-up visual attention being one part of a broader criteria for selecting click-points. Alternately, these click-points might be chosen according to some other phenomenon that happens to have a non-trivial intersection with this model of bottom-up visual attention.

These results raise interesting questions regarding how visual attention relates to user choice in graphical passwords. For example, might some users choose the first point according to bottom-up visual attention, and then the rest in a top-down manner such that they are somehow similar to the first? Alternately, might the entire process be top-down, based on whether the user can find five objects that are similar in some way? Such a top-down theory would be substantially more difficult to model an attack on, but if possible to implement, its results might offer interesting insight.

Finally, our attacks could be used to help inform more secure design choices in implementing PassPoints-style graphical passwords. Proactive checking rules for PassPoints-style graphical passwords might be created based on the click-order pattern attacks herein; for example, disallowing LINE or DIAG

patterns (for all laziness modes), and disallowing passwords where too few click-points are further than 150 pixels away from the previous click-point. Of course, any such proactive checking rules would need to be tested to ensure that the usability impact is acceptable and that security is not impacted in other unexpected ways.

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